**Electrification of the transport System: Impacts of national policies vs external drivers. A case study for Pakistan.**

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**Abstract**

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# Introduction

# Background

Background on electrification trends in general, role in decarbonization and regional projections across the globe

# Literature Review

1. Lit review and role of EV penetration global/national
2. Price takers vs Price makers.
3. Developing vs Developed.
4. Uncertainties in demand growth.
5. Lack of other studies

# Research Question

Questions addressed in this analysis:

* What are the impacts of incentives on EV penetration?
* What is the sensitivity of EV adoption to technological and cost development?
* What are the impacts on power supply requirements and fuel consumption?
* What are the impacts on vehicular and power sector emissions?

# Methodology

# Cross-Model Links (GCAM, PLEXOS, SEP)

Several models are used in tandem for this analysis. GCAM is primarily used to develop EV adoption curves and resulting emissions impacts. The Sustainable Energy for Pakistan (SEP) Project team then uses the GCAM EV adoption curves in their EVM model to calculate EV electricity requirements and charging profiles and EV-displaced vehicle fuels. These results are then provided to the National Transmission & Despatch Company (NTDC), Pakistan’s national grid operator, who uses the adoption curves in their PLEXOS model to look at the impact of different adoption scenarios on power demand and electricity infrastructure needs. Though GCAM also models interactions with the power sector and fuel consumption, PLEXOS is a more detailed energy market model, and NTDC’s modeling is more directly tied to fuel mix and expansion plans for Pakistan’s power sector under NTDC’s Indicative Generation Capacity Expansion Plan. SEP then uses the PLEXOS results in their EVM model to analyze fuel requirements for additional power generation and associated fuel costs.

# GCAM Overview

Part of the analysis for this report was conducted using the Global Change Assessment Model (GCAM). GCAM is a global, multi-sector, market equilibrium model. It represents the behavior of and interactions between the global energy, water, agriculture and land use, economy, and climate systems. There are 32 geopolitical regions in GCAM, one of which is Pakistan. The model runs in 5-year time steps through the end of the century, with 2010 as the final calibration year. In each period, the model calculates equilibria across all global and regional markets.

# GCAM Transport Sector Details

GCAM has a high level of detail represented in the transportation sector. The sector is divided into four final demands: passenger, freight, international aviation, and international shipping. The demand for transportation services (in passenger-kilometers or ton-kilometers) in each region and time period is driven by GDP, population, cost of transport services, and income and price elasticities. The final demands are further broken down into different modes (e.g., road, rail), sub-modes (e.g., bus, light duty vehicle), size classes (e.g. compact car, moped), and technologies (e.g. liquids, hybrid liquids, battery electric). At the passenger subsector level, a time value, determined by the wage rate (per-capita GDP divided by the number of working hours in a year) and exogenously specified vehicle speed, is incorporated into the competition between transport modes. This causes a shift towards faster modes of transportation as incomes increase. Non-fuel costs, such as capital and maintenance costs, are exogenously specified for each transport technology. Fuel costs are endogenously calculated based on demand and regional supply curves. These costs are totaled and levelized to a single monetary cost per passenger-kilometer or ton-kilometer. The model then calculates market shares for each transport technology based on a logit choice specification, which avoids a “winner-take-all” result for the lowest cost option.[[1]](#footnote-1) Some transportation vehicles are vintaged, with older vehicles retiring over time and new vehicles added in each future model year.

Transport service demands for each GCAM region are calibrated in the base year so that transportation energy consumption matches IEA energy balance data. IEA data provides total fuel consumption in the road transportation sector; detailed breakdowns beyond this level (e.g. between passenger and freight, modes, and size classes) are based on regional data and assumptions. The default assumptions and sources for the transportation module of GCAM are documented in Mishra et al. 2013. However, we update many assumptions to capture more recent data on EV technological development, as well as Pakistan-specific transport characteristics based on input from collaborators.[[2]](#footnote-2) As non-fuel costs and other parameters such as intensity are exogenous, consumer choices do not influence the characteristics of the transport technologies themselves. For example, higher EV adoption rates would not result in faster technological improvement and cost reduction.

Transport technologies in GCAM each have a share weight value, which serves as a representation of consumer preferences in two ways: first, to calibrate the model to historical IEA energy balance data and absorb regionally specific preferences, and second, to allow new technologies to be phased in gradually. EV share weights for all vehicle types are calibrated to 0 in the base year and gradually increase to 1, on par with conventional liquids vehicles.

# GCAM Scenario Details

* Baseline Assumptions
* Policies
  + NEVP overview
  + Representation in GCAM
* Technological/Costs/Prices
  + Cost adjustments for Pakistan

**Baseline Assumptions**

For this analysis, we focus on road transport and run the model up to 2050. Pakistan’s road technologies in GCAM include two-wheelers (mopeds, motorcycles, and scooters), three-wheelers, cars (mini cars, subcompact cars, compact cars, and multipurpose vehicles), buses, and trucks (0-2 tons, 2-5 tons, 5-9 tons, and 9-16 tons). All of these transport classes have both conventional liquids and BEV technologies represented. All except two-wheelers also have natural gas vehicles available, and cars additionally have hybrid liquids and fuel cell electric vehicle technologies. We use vehicle cost assumptions based on data from NREL (Jadun et al. 2017) as well as data on battery costs from a review of the literature (see appendix A.3.2. for more details). Energy intensity comes from NREL, and other assumptions such as load factor, annual distance traveled, and base-year energy use come from Mishra et al. 2013.

**NEVP Overview**

The government of Pakistan (GoP) recently approved targets for EV penetration under the National Electric Vehicle Policy (NEVP). These are summarized in the table below:



Policy objectives include reducing greenhouse gas emissions and air pollution, reducing the oil import bill, using electricity at off-peak times and reducing idle capacity payments, and supporting domestic manufacturing of electric vehicles. To increase EV adoption and achieve these goals, the NEVP proposes numerous policy measures. These include sales tax exemptions for locally produced EVs; exemption from registration fees and annual token tax; lower duties for vehicle imports; reduced or eliminated duties for imports of EV-specific materials and parts used in local production; government procurement of electric bus and truck fleets; EV-specific zones in high density areas; and expansion of public charging infrastructure.

**NEVP Representation in GCAM**

For our baseline (no policy) scenario, we assume no EV incentives. Pakistan’s vehicle taxes, import duties, and fees apply equally to all vehicle technologies. We assume current levels of localization of ICEV production and no localization of EV production, in the absence of policies supporting this.

In our policy scenarios, we model only the monetary EV incentives, which affect vehicle costs. We model the NEVP tax, duty, and fee incentives under no localization of EV production, gradual localization, and accelerated localization, as incentives vary for local versus imported vehicles and materials and have a significant effect on the results. We run the policy scenarios on top of slow and rapid EV technology advancement scenarios to provide a range of possible cost pathways, as future technology and cost development remains quite uncertain.

# PLEXOS Overview

# SEP Model Overview

# Results

# GCAM Baseline Results

# GCAM Scenario Results – EV adoption, emissions impacts

# PLEXOS Results – power demand, infrastructure needs

# SEP Model Results – fuel needs by type, fuel costs

# Discussion & Conclusions

1. Summary of results
2. Implications for other regions
3. Local policies versus external forces

# References

# Appendices

# Pakistan-specific changes to core GCAM

## Socioeconomic assumptions

We began by adjusting GCAM’s default projections for Pakistan to better align with projections made by stakeholders within Pakistan. We used Shared Socioeconomic Pathway (SSP) 5 assumptions for population and GDP growth rather than the default of SSP 2, as these aligned better with data from the Pakistan Planning Commission. GDP growth rate assumptions were also updated to reflect the latest IMF data on GDP growth rates.[[3]](#footnote-3)

## Power sector changes

Default GCAM power sector projections for Pakistan were adjusted based on the 2019 Indicative Generation Capacity Expansion Plan (IGCEP) 2018-40. This report gives an overview of Pakistan’s existing power system, forecasts future electricity demand, and presents the results of expansion planning studies conducted by the Load Forecast and Generation Planning (LF&GP) of Power System Planning (PSP), National Transmission and Dispatch Company (NTDC). In addition, we use updated capital costs for intermittent and dispatchable renewable technologies, which come from NREL’s Annual Technology Baseline 2018 edition.

### Fossil Generation

As the IGCEP does not include plans to expand generation from refined liquids, we set the refined liquids share weight in electricity generation to 0 after 2020. We also increase coal share weights to reflect plans in the IGCEP to expand coal-fired power generation. However, we do not fully match IGCEP in this case because of feedback that the government of Pakistan aims to revise the coal generation plan from IGCEP downward in the next version.

Refined liquids share weights

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | **2010** | **2015** | **2020** | **2025** | **2030** | **2035** | **2040** | **2045** | **2050** |
| **Default** | 1 | 0.95556 | 0.911111 | 0.866667 | 0.822222 | 0.777778 | 0.733333 | 0.688889 | 0.644444 |
| **Adjusted** | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Coal share weights

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | **2010** | **2015** | **2020** | **2025** | **2030** | **2035** | **2040** | **2045** | **2050** |
| **Default** | 0.00081317 | 0.00856 | 0.010038 | 0.01179 | 0.013864 | 0.016317 | 0.019215 | 0.022637 | 0.026672 |
| **Adjusted** | 0.00081317 | 0.250407 | 0.15 | 0.25 | 0.5 | 0.7 | 0.8 | 0.7 | 0.6 |

### Hydropower

Hydropower electric generation in GCAM is given as fixed output. We base hydro generation for 2020-2040 on the hydro generation projections given in the IGCEP. From 2040-2050, we assume constant linear increase in hydro generation at the 2020-2040 average rate. We hold hydro generation constant beyond 2050, as the analysis for this project only goes through 2050.

Pakistan hydro generation (EJ):

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | **2015** | **2020** | **2025** | **2030** | **2035** | **2040** | **2045** | **2050** |
| **Default** | 0.117706 | 0.120892 | 0.124078 | 0.127264 | 0.13045 | 0.140089 | 0.149728 | 0.159367 |
| **Adjusted** | 0.117706 | 0.143935 | 0.238579 | 0.422274 | 0.530093 | 0.573574 | 0.66302 | 0.749482 |

### Nuclear

Share weights for nuclear technologies were increased between 2015 and 2050 to align nuclear generation in GCAM with IGCEP plans. For 2020-35, we calculated generation based on capacities of IGCEP committed nuclear plants, assuming a capacity factor of 0.8.[[4]](#footnote-4) We then iterated on the nuclear share weights to get generation close to the IGCEP projections.

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | **2010** | **2015** | **2020** | **2025** | **2030** | **2035** | **2040** | **2045** | **2050** |
| **Default** | 0.024771 | 0.05 | 0.05 | 0.058333 | 0.066667 | 0.075 | 0.083333 | 0.091667 | 0.1 |
| **Adjusted** | 0.024771 | 0.05 | 0.5 | 1 | 1 | 1 | 0.1 | 0.1 | 0.1 |

## Industry changes

After making these adjustments to the power sector, electricity generation was significantly higher in GCAM in early years compared other sources. In particular, GCAM industrial electricity in 2015 was higher than reported by the Pakistan Energy Yearbook and International Energy Agency. We added an industry electricity fuel preference elasticity of -0.5 and decreased the industrial income elasticity by 50% to tune industrial and total electricity consumption closer to these data sources.

## Transportation changes

### General updates to transportation assumptions

Each region in GCAM has a specific set of vehicle classes, and classes have different input assumptions. Pakistan’s vehicle classes and their assumptions are summarized in the table below:

|  |  |  |  |
| --- | --- | --- | --- |
| **Mode** | **Size classes** | **Technologies** | **Input assumptions** |
| 2-wheel LDV | Moped  Motorcycle (50-250cc)  Scooter | Liquids  BEV | Annual travel per vehicle  Base year energy use  Intensity  Load factor  Speed  Capital costs (purchase)  Capital costs (infrastructure)  Capital costs (purchase)  Operating costs (maintenance)  Operating costs (registration and insurance)  Operating costs (tolls) |
| 3-wheel LDV | Three-Wheeler | Liquids  Natural Gas  BEV | Annual travel per vehicle  Base year energy use  Intensity  Load factor  Speed  Capital costs (total)  Operating costs (total non-fuel) |
| 4-wheel LDV | Mini Car  Subcompact Car  Compact Car  Multipurpose Vehicle | Liquids  Hybrid Liquids  Natural Gas  BEV  FCEV | Annual travel per vehicle  Base year energy use  Intensity  Load factor  Speed  Capital costs (purchase)  Capital costs (infrastructure)  Capital costs (purchase)  Operating costs (maintenance)  Operating costs (registration and insurance)  Operating costs (tolls) |
| Bus | Bus | Liquids  Natural Gas  BEV | Base year energy use  Intensity  Load factor  Speed  CAPEX and non-fuel OPEX |
| Freight truck | Truck (0-2t)  Truck (2-5t)  Truck (5-9t)  Truck (9-16t) | Liquids  Natural Gas  BEV | Base year energy use  Intensity  Load factor  CAPEX and non-fuel OPEX |
| Walk | Walk | N/A | Base year service output  Speed |
| Cycle | Cycle | N/A | Base year service output  Speed |
| Rail | Passenger Rail  Freight Rail | Coal (freight only)  Electric  Liquids  Tech-Adv Electric  Tech-Adv Liquids | Base year energy use  Intensity  Load factor  CAPEX and non-fuel OPEX Operating subsidy  Speed (passenger only) |
| Air Domestic,  Air International | Air Domestic,  Air International | Liquids | Base year energy use  Intensity  Load factor  Speed  CAPEX  Non-fuel OPEX |
| Ship Domestic, Ship International | Ship Domestic,  Ship International | Liquids | Base year energy use  Intensity  Load factor  CAPEX and non-fuel OPEX |

These assumptions are contained in the file UCD\_trn\_data\_CORE.csv. We use an updated version of the database with several changes from the core GCAM version based on Mishra et al (2013). The updated version contains vehicle assumptions for all model years (in 5-year timesteps rather than 15). Battery electric technologies were added for trucks and buses in all regions. Adding new technologies also requires corresponding additions in other files - share weights (in A54.globaltranTech\_shrwt.csv), interpolation rule (A54.globaltranTech\_interp.csv), lifetimes (A54.globaltranTech\_retire.csv), and mappings (mappings/UCD\_techs.csv). Cost assumptions for both BEV and liquids cars, trucks, and buses were updated based on NREL’s Electrification Futures Study (Jadun et al. 2017)[[5]](#footnote-5). This report contains slow, moderate, and rapid electrification development pathways, which were developed into three sets of vehicle assumptions. BEV costs and energy intensity vary between these technology advancement scenarios. The new assumptions also add natural gas truck infrastructure costs, and update liquids vehicle energy intensities to match CAFÉ standards in the US (lagged by 5 years for other regions). Finally, we delete operating subsidies for buses across all technologies and regions. In the original UCD assumptions the subsidies made the user cost equal across technologies to reflect equal fares for consumers – however, this was no longer the case after updates to vehicle costs. In addition, we aim capture the actual cost differences between bus technologies in order to model how these impact EV adoption, so using unsubsidized costs is more appropriate.

In the core version of GCAM, only car and truck technologies are vintaged. We add this feature for buses, 2-wheelers, and 3-wheelers by adding lifetimes and retirement functions. For buses, these were copied from light trucks, which have a lifetime of 25 years. For 2- and 3-wheelers, the maximum lifetime is 15 years. In the retirement function, the half-life is 8 years and steepness is 0.3.

To reflect current levels of EV penetration, we modify the share weight assumptions to show near-zero EV penetration in 2020. Share weights increase to 1 (indicating parity with conventional liquids vehicles on all non-cost characteristics, such as availability, functionality and consumer preferences) in 2030 for light-duty vehicles and 2040 for buses and freight trucks. Share weights increase more rapidly for 2- and 3-wheelers to reflect lower barriers to adoption for these smaller vehicles.

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
|  | **2010** | **2015** | **2020** | **2025** | **2030** | **2035** | **2040** |
| **2/3W LDV** | 0 | 0.025 | 0.05 | 0.6 | 1 | 1 | 1 |
| **4W LDV** | 0 | 0.025 | 0.05 | 0.4 | 1 | 1 | 1 |
| **Truck, bus** | 0 | 0.025 | 0.05 | 0.4 | 0.6 | 0.8 | 1 |

EV share weights:

### Battery cost curves update

Recent data shows that battery pack costs have fallen faster than widely projected (Goldie-Scot 2019; Berckmans et al. 2017; Holland 2018; Kittner, Lill, and Kammen 2017). For example, according to Bloomberg New Energy Finance, battery costs in 2019 had dropped to $156 per kWh (BNEF 2019), which the EFS projected would be only be reached by between 2025 and 2030 in the rapid case, 2040 in the moderate case, and not until after 2050 in the slow case (Jadun et al. 2017).We modify the vehicle costs for each curve based on more aggressive battery cost projections. Intensity and infrastructure costs also vary between these technology advancement scenarios based on the EFS data, but we leave these unchanged and only update capital costs based on the new battery cost curves below.

|  |  |  |  |
| --- | --- | --- | --- |
| New battery cost curves (2018$/kWh)[[6]](#endnote-1) | | | |
|  | **Slow** | **Moderate** | **Rapid** |
| 2019 | 156 | 156 | 156 |
| 2020 | 146.3 | 140.5 | 123 |
| 2025 | 97.5 | 84.9 | 57.1 |
| 2030 | 87.8 | 62 | 50 |
| 2035 | 78.1 | 55 | 44 |
| 2040 | 74.7 | 50.8 | 38 |
| 2045 | 71.3 | 46.3 | 33.4 |
| 2050 | 67.9 | 42.1 | 28.9 |

|  |  |  |  |
| --- | --- | --- | --- |
| EFS (NREL) battery cost curves (2018$/kWh) | | | |
|  | **Slow** | **Moderate** | **Rapid** |
| 2016 | 285 | 285 | 285 |
| 2020 | 269 | 257 | 242 |
| 2025 | 248 | 222 | 188 |
| 2030 | 229 | 188 | 136 |
| 2035 | 209 | 167 | 93 |
| 2040 | 200 | 159 | 83 |
| 2045 | 191 | 149 | 83 |
| 2050 | 183 | 140 | 83 |

Battery cost curves and sources



#### Battery vintaging factors

We calculate battery vintaging factor to account for batteries not lasting full vehicle lifetime. We assume batteries last 10 years and take the weighted average of battery packs needed over vehicle lifetime, using the retirement function to get share of vehicles still in use after certain timesteps.



For cars, buses, and light duty trucks (vehicles with 25-year max lifetime), the battery vintaging factor is 1.17, and for medium and heavy-duty trucks (vehicles with 40-year max lifetime) it is 1.35. For 2 and 3-wheelers, we assume no battery replacement is necessary.

#### **4W LDVs**

We update capital costs (purchase) to reflect our new battery cost curves. We extract the battery share of total purchase cost for BEV 100 compact cars by year from Autonomie data on vehicle component costs (Moawad et al. 2016) [[7]](#endnote-2). This data provides cost projections for vehicle components under low, average, and high non-battery technology advancement curves; we use the average case for this analysis. We then extract the percent difference between NREL’s battery cost assumptions and our new curves by year. For each size class, the new purchase cost is computed as:

New cost = old cost \* (1 – ((battery cost % change from NREL) \* (battery share of cost) \* (battery vintaging factor))

#### **2-wheelers**

For 2-wheelers, new purchase costs were calculated largely the same way as for 4-wheel LDVs. However, we did not have data on battery share of cost from Autonomie (Moawad et al. 2016). We assume the battery is 37.5% of vehicle cost in 2020. This is based on assumption that 50% of the total cost of 2- and 3-wheelers are due to EV components and batteries constitute 75% of the EV component cost, which is generally true for compact cars from the Autonomie data. We assume the battery share of purchase cost decreases at the same rate as it does for compact cars, from Moawad et al. We update costs based on the new battery curves after scaling for cost parity in 2020 (described below) and creating Slow, Moderate, and Rapid curves using NREL’s battery costs and the same battery cost share as described above, because default 2- and 3-wheel costs from UCD study do not provide a range of costs.

#### **3-wheelers**

For 3-wheelers, we modify capital costs (total). New costs are calculated the same way as for 2-wheel and 4-wheel LDVs, but since the assumption is total capital costs rather than purchase, we add an extra factor for the purchase cost share of capital cost, so costs are calculated as:

New cost = old cost \* (1 – ((battery cost % change from NREL) \* (battery share of cost) \* (purchase cost share of capital cost) \* (battery vintaging factor))

Default taxes and fees for the Southeast Asia region are 35% of the price (Mishra et al. 2013), so 65% of the total is assumed to be purchase price. Like 2-wheelers, we assume BEV cost parity with ICEVs in 2020 (see below).

#### **Trucks**

There is only one cost variable for trucks, CAPEX and non-fuel OPEX ($/vkm), so we modify this by estimating the battery share of the levelized cost. Due to lack of data on the cost components of medium and heavy-duty truck classes, we use the battery share of purchase cost for BEV 100 pickup trucks from the Autonomie data (again using the average non-battery tech curve) for all truck classes. We estimate the purchase cost share of non-fuel levelized cost based on the component cost shares for compact cars using 2020 Moderate Advancement costs. Thus, the new costs are calculated as:

New cost = old cost \* (1 – ((battery cost % change from NREL) \* (battery share of cost) \* (share of capital cost in LCOD) \* (battery vintaging factor))

#### **Buses**

Like trucks, we modify CAPEX and non-fuel OPEX. We estimate the battery share of cost based on recent electric bus prices in China, the battery size of Proterra’s 440 kwh e-bus, and the 2019 battery pack price of $156/kWh[[8]](#footnote-6). Based on this, the share is 12.5% of cost in 2020, and we decrease it over time at same rate as the battery share of cost for BEV 100 pickup trucks from Moawad et al (2016). The capital cost share of non-fuel levelized cost comes from the EFS report. (figure 13 data). New costs are calculated as:

New cost = old cost \* (1 – ((battery cost % change from NREL) \* (battery share of cost) \* (share of capital cost in LCOD) \* (battery vintaging factor))

### Pakistan-specific transportation changes

We also make a number of updates to the assumptions for the Southeast Asia region, which contains Pakistan (Pakistan is not its own region in the vehicle assumptions). We add BEV 3-wheelers as a technology to reflect locally available vehicle types. Based on feedback from collaborators at SEP, we change 3-wheeler speed from 36 to 25 kilometers per hour and increase annual travel per vehicle from 8478 kilometers per year to 32,000 kilometers per year.

We update the cost assumptions for 2- and 3-wheelers in Southeast Asia. As NREL’s Electrification Futures Study (Jadun et al. 2017) does not report data for these vehicles, we rely on market data in Pakistan to determine current costs. A representative gasoline-powered motorcycle model in Pakistan costs about $800, about 59% of the cost assumption in the UCD database, so we scale all liquids 2-wheeler purchase costs by this value. Based on feedback from collaborators at SEP, electric 2-wheelers are already at levelized cost parity with conventional ICE 2-wheelers in Pakistan. Therefore, we back calculate purchase costs for BEVs in 2020 by class using ICEV cost assumptions and assuming equal levelized costs. After 2020, costs decrease according to the battery costs given in the three technology advancement pathways.

As BEV 3-wheelers do not exist as a technology in the current core GCAM and Pakistan-specific cost data is limited, we estimate BEV 3-wheel capital costs in 2020 using the ratio of liquids motorcycles to 3-wheelers in Southeast Asia in the original UCD database. This ratio (1.37) is then multiplied by the BEV motorcycle cost calculating purchase costs under levelized cost parity. After 2020, costs decrease according to the battery costs given in the three technology advancement pathways.

We also update BEV mini car costs and intensity to match the assumptions for India. This was the only car class and technology where assumptions did not match those in India, for unclear reasons, so we correct this discrepancy.

The infrastructure capital cost assumptions for BEVs come from Jadun et al. (2017), but these were based on costs in the U.S. A large portion of these costs were for labor associated with installation and upgrades to residential electrical systems. However, labor costs are much lower in Pakistan and many households have electrical service with a higher voltage compared to the U.S. We assume one charger required per vehicle, a typical residential power plug with 230V/10A and 100-35 km of driving daily. Based on market data in Pakistan, a level-2 charger costs $350-500, installation is $50-100, and residential electrical service upgrades cost $80-135. We assume an average charging infrastructure capital cost of $580 for 4-wheel LDVs. We remove charging costs entirely for 2-wheelers, as vehicle specifications indicate 2-wheeler batteries are sufficiently small that no additional charging infrastructure for residential use is required. We do assume 3-wheelers require the $580 charging infrastructure cost because of the high annual distance travelled per vehicle.

Collaborators at SEP collected information on typical maintenance costs for company and staff vehicles, as well as information from an informal survey of auto workshops, vehicle drivers, etc., around Islamabad. We use this to adjust our vehicle maintenance cost assumptions for LDVs. Actual average maintenance costs could be much lower than the values collected, however, as many owners tend to pay for maintenance only when unavoidable. We scale the values by 70% to represent more realistic maintenance.

In addition, market survey data provided by collaborators at ANL indicated that capital costs for light trucks and buses are significantly lower in Pakistan than the US. For the data available, vehicles in Pakistan were about 40% of the cost of comparable US vehicles. As GCAM truck costs are based on US data and do not vary by region, unlike LDVs, and bus cost assumptions are nearly identical between the US and Pakistan, we scale costs for buses, 0-2 ton trucks, and 2-5 ton trucks to represent this regional knock-down factor. Cost assumptions for buses and trucks are given as levelized non-fuel cost (per vehicle-kilometer traveled); we use cost assumptions for compact cars to calculate that purchase costs are about 76% of non-fuel levelized costs, and apply the 40% capital cost regional knockdown factor to that share of the levelized cost. This applies to all technologies within these classes. The cost difference appears to be less significant for heavy-duty trucks, so we leave these costs unchanged.

Bus costs were levelized by dividing by annual distance traveled of 51,708 km/year, while SEP assumes buses travel 72,000 km per year. For consistency, we scale bus costs for all technologies by 51708/72000 to implicitly change annual distance traveled. We also adjust BEV truck load factor assumptions for consistency across technology advancement scenarios. BEV truck load factors are set to 80% of liquids load factors in 2020 and linearly increase to be equal with liquids trucks in 2050. This change was made for Southeast Asia only.

The GCAM data system uses a default discount rate of 10% for consumer vehicle purchases. It should be noted that this value is only used to calculate a fixed charge rate, which converts capital costs to annualized costs as part of the levelized cost calculation. We change the discount rate to 15%, based on loan rates of 20-21% in Pakistan today[[9]](#footnote-7) and average inflation of 5.5% over the past five years.[[10]](#footnote-8)

# EV analysis

## Policy scenarios

The table below summarizes the EV policy scenarios. These are run in combination with Slow and Rapid Advancement cost pathways (see below), for a total of eight scenarios.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Scenario No.** | **Scenario** | **Scenario Shorthand** | **Description** | **Applies to** |
| 1 | Reference | *NoPolicy\_NoLoc* | No policies supporting EV adoption EV duties/taxes/registration based on assumption of no local manufacturing | Consumer vehicles (2, 3, 4-wheel LDVs) Buses Freight trucks |
| 2 | NEVP EV Duty Reductions, no EV localization | *NEVP\_NoLoc* | National Electric Vehicle Policy (NEVP) recommendations for duty/tax/registration reductions for EVs, with no development of local manufacturing | Consumer vehicles (2, 3, 4-wheel LDVs) Buses Freight trucks |
| 3 | NEVP EV Duty Reductions, gradual EV localization | *NEVP\_GradLoc* | National Electric Vehicle Policy (NEVP) recommendations for duty/tax/registration reductions for EVs, with gradual development of local manufacturing | Consumer vehicles (2, 3, 4-wheel LDVs) Buses Freight trucks |
| 4 | NEVP EV Duty Reductions, accelerated EV localization | *NEVP\_AccelLoc* | National Electric Vehicle Policy (NEVP) recommendations for duty/tax/registration reductions for EVs, with accelerated development of local manufacturing | Consumer vehicles (2, 3, 4-wheel LDVs) Buses Freight trucks |

Pakistan’s vehicle taxes and duties are given as a percentage of the vehicle purchase price. For ICEVs, these are based Pakistan’s Automotive Development Policy 2016-2021, along with data and assumptions on local manufacturing and imports of conventional liquids vehicles. The final duties, taxes, and fees are assumed to be constant over time, and are shown in the table below:

**ICEVs:**

|  |  |
| --- | --- |
| **Vehicle Category** | **Final Duty, Tax & Fees (% of purchase price)** |
| Two-wheelers | **27.2%** |
| Three-wheelers | **29.6%** |
| Cars | **35.6%** |
| Buses | **35.1%** |

**EVS (proposed BEV tax/duty/fee reductions under National Electric Vehicle Policy):**

The NEVP proposes varying taxes, duties, and fees for imports and local production. For imports, duties differ depending whether materials and parts are EV-specific or not, and whether whole vehicle imports are completely built up (CBU) or complete knock down (CKD) units. To model the NEVP, we make assumptions about the level of EV production localization for each vehicle class. There are three localization scenarios: a base case with no EV localization, a gradual localization case, and an accelerated localization case. EV benefits under the NEVP are largely proposed to last 7 years, but as GCAM uses 5-year time steps, we model the NEVP over 10 years, from 2020 to 2030. Taxes, duties, and fees under the NEVP localization scenarios are given as a percentage of the purchase price.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Base Case (no localization)** |  |  |  |  |
| **Vehicle Category** | **2020** | **2025** | **2030** | **2035** |
| Two-wheelers | 3% | 19% | 35% | 58% |
| Three-wheelers | 3% | 19% | 35% | 58% |
| Cars | 3% | 19% | 35% | 63% |
| Tractors | 2% | 19% | 36% | 60% |
| Buses | 2% | 19% | 36% | 60% |
| Trucks | 2% | 19% | 36% | 60% |
|  |  |  |  |  |
| **Gradual Localization** |  |  |  |  |
| **Vehicle Category** | **2020** | **2025** | **2030** | **2035** |
| Two-wheelers | 4% | 15% | 19% | 39% |
| Three-wheelers | 4% | 15% | 19% | 39% |
| Cars | 7% | 18% | 31% | 58% |
| Tractors | 2% | 17% | 30% | 52% |
| Buses | 2% | 18% | 32% | 55% |
| Trucks | 2% | 17% | 31% | 54% |
|  |  |  |  |  |
| **Accelerated Localization** | Final taxes, duties, and fees | | | |
| **Vehicle Category** | **2020** | **2025** | **2030** | **2035** |
| Two-wheelers | 9% | 13% | 10% | 28% |
| Three-wheelers | 9% | 13% | 10% | 28% |
| Cars | 8% | 13% | 14% | 37% |
| Tractors | 2% | 15% | 23% | 44% |
| Buses | 2% | 17% | 29% | 51% |
| Trucks | 2% | 16% | 25% | 47% |

These use the following localization assumptions:



We also make the following assumptions about the share of EV-specific components by vehicle type (since custom duties are lowered under the NEVP for EV-specific parts):

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Vehicle Category** | **Allocation of EV Specific Material & Parts6** | | | |
| **2020** | **2025** | **2030** | **2045** |
| Two-wheelers | 30% | 25% | 21% | 19% |
| Three-wheelers | 30% | 25% | 21% | 19% |
| Cars | 30% | 25% | 21% | 19% |
| Tractors | 55% | 48% | 45% | 40% |
| Buses | 55% | 48% | 45% | 40% |
| Trucks | 55% | 48% | 45% | 40% |

Since vehicle classes have different types of capital cost assumptions, we implement the cost multipliers based on Pakistan’s taxes, duties, and fees in different ways. For 2-wheel and 4-wheel LDVs, we simply change capital costs (other), which represents sales tax and other costs not included in the manufacturer’s suggested retail price, to the given percentage of the purchase price. For 3-wheelers, taxes are included in capital costs (other), and for Southeast Asia average 35% of purchase price (Mishra et al. 2013). We adjust that 35% to the given taxes, duties, and fees multiplier for each scenario. For buses and trucks, the cost assumption is levelized CAPEX and non-fuel OPEX. We use the cost assumptions for multipurpose vehicles (under the Moderate Advancement scenario) to estimate the purchase cost share of levelized cost. This is about 54% for ICEVs and 58% for BEVs, because of the higher capital costs of BEVs. We use these shares to apply taxes, duties, and fees multipliers to truck and bus costs.

## Sensitivity analysis

Research has shown that consumers considering energy efficient technologies with higher capital but lower operating costs, including EVs, consistently discount the future savings they will receive (Lee and Lovellette 2011; Gallagher and Muehlegger 2011). As a sensitivity to highlight the importance of accurate perceptions of the cost advantages of EVs, for instance to demonstrate the effect of informational campaigns, we run a high and low case (slow advancement, NEVP gradual localization and rapid advancement, NEVP accelerated localization) with higher EV operating costs. We calculate new operating costs for each LDV size class to represent a 30% discounting of future operational cost savings. Ideally this would be done by discounting both maintenance and fuel costs at a 30% rate, but as fuel costs are modeled endogenously, we use the fuel costs from the model output to calculate new maintenance costs that, when levelized, encapsulate higher discounting of all operating costs. We use this method to model consumer behavior because this effect was not fully captured in the share weights, as research shows discounting of future savings is a persistent effect even with mature technologies.

We also ran a sensitivity isolating the main policy measures included in the NEVP, to see which are most impactful for EV adoption. The measures isolated were the goods and services (GST) tax reductions, custom duty reductions on completely built up (CBU) imports, and custom duty reductions on complete knock down (CKD) imports. We calculate new tax, duty, and fee multipliers for purchase costs to show the effect of each policy lever, and run these on top of the high and low cases above.

1. <https://jgcri.github.io/gcam-doc/energy.html#transportation> [↑](#footnote-ref-1)
2. See appendix A.3 for details on updates to transportation assumptions. [↑](#footnote-ref-2)
3. Check the reasoning/sources behind these changes (and whether these should still be used as baseline assumptions in all scenarios). [↑](#footnote-ref-3)
4. <http://world-nuclear.org/getattachment/Our-Association/Publications/Online-Reports/World-Nuclear-Performance-Report-2018-Asia-Edition/world-nuclear-performance-report-asia-2018.pdf.aspx> [↑](#footnote-ref-4)
5. For cars, NREL’s cost data was pegged to the UCD size class of US midsize car. The ratios between vehicle costs in the original UCD database were used to scale the updated US midsize car costs to other size classes and regions. For trucks, a cost per ton was calculated and used to scale costs to all truck size classes (determined by the midpoint of the load factor). Truck costs do not vary by region. [↑](#footnote-ref-5)
6. |  |
   | --- |
   | Sources |
   |  |
   | * Baik, Y., Hensley, R., Hertzke, P., & Knupfer, S., (March 2019). Making electric vehicles profitable. Retrieved from: https://www.mckinsey.com/industries/automotive-and-assembly/our-insights/making-electric-vehicles-profitable |
   |  |
   | * Moawad, A., Kim, N., Neeraj, S., & Rousseau, A., (2016). Assessment of Vehicle Sizing, Energy Consumption, and Cost Through Large-Scale Simulation of Advanced Vehicle-Technologies (ANL/ESD-15/28). Retrieved from https://www.autonomie.net/pdfs/Report%20ANL%20ESD-1528%20-%20Assessment%20of%20Vehicle%20Sizing,%20Energy%20Consumption%20and%20Cost%20through%20Large%20Scale%20Simulation%20of%20Advanced%20Vehicle%20Technologies%20-%201603.pdf |

   [↑](#endnote-ref-1)
7. <https://www.autonomie.net/docs/ANL%20-%20BaSceFY17%20-%20Autonomie%20-%20Merge_Results_052317_181101.xlsx> [↑](#endnote-ref-2)
8. Based on market examples of a 395k-593k (“BYD K9” 2020) and $300-900k per bus in China (Poon 2019). Proterra is producing an e-bus with 440 kWh battery capacity (“Proterra: US Record for Electric Bus Battery Capacity - Sustainable Bus” 2019), with total cost ~$750k (Stromsta 2019). [↑](#footnote-ref-6)
9. <https://www.mawazna.com/loans/carLoanSteps/2?car_value=2980000&loan_amount=2533000&loan_period=7&model_year_value=&banks_included=1%2C10%2C11%2C15%2C19%2C20&city=Islamabad&model_year=2020&car_make=1&down_payment=15&loanTerm=7&source_of_income=1&income_value=25000&bank=1&bank=10&bank=11&bank=15&bank=19&bank=20> [↑](#footnote-ref-7)
10. <https://www.statista.com/statistics/383760/inflation-rate-in-pakistan/> [↑](#footnote-ref-8)